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Distributed Manipulation of Multiple Objects using Ropes

Distributed Manipulation of Multiple Objects using Ropes Bruce Donald , Larry Garnepy, and Daniela Rus Dartmouth Computer Science Department Abstract This paper describes a system in which multiple robots cooperate to move multiple objects such as groups of boxes using a constrained prehensile manipulation mode, by wrapping ropes around them. The system consists of three manipulation

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Distributed Manipulation

Distributed Manipulation of an object by a swarm of robots. Created by Jon Fink and Nathan Michael, GRASP Lab, UPENN.

Distributed Manipulation

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Distributed manipulation can be performed by many types of mechanisms at different scales. Due to the recent advances of Memis (micro-electro-mechanical system) technology, it has become feasible to quickly manufacture distributed micro-manipulators at low cost. One such system is an actuator array where hundreds of micro-scaled actuators transport and manipulate small objects that rest on them.