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Abstract This paper deals with transversal motion and vibration control for a flexible tower-like transport system that uses an elevator to lift payloads vertically. Applying a lumped modeling method presented by Seto and a LQ-

based control system, the controller to achieve good performance is designed. The purpose of this research is to control motion and vibration under moving flexible

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Because the forced vibration that initiated the motion is a single instance of a short-lived, momentary force, the vibrations ultimately cease. The bobblehead is said to experience damping . Damping is the tendency of a vibrating object to lose or to dissipate its energy over time.

What is the difference between oscillation and vibration ...

Oscillation is a definite distance covered by the movement about its equilibrium position, vibration is referred to the physical change brought about due to movement of the body. Oscillation can be seen in the swinging of a pendulum clock and vibr

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Motion and vibration control is a fundamental technology for the development of advanced mechanical systems such as mechatronics, vehicle systems, robots, spacecraft, and rotating machinery.

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Description : Motion and vibration control is a fundamental technology for the development of advanced mechanical systems such as mechatronics, vehicle systems, robots, spacecraft, and rotating machinery. Often the implementation of high performance, low power consumption designs is only possible with the use of this technology. It is also vital to the mitigation of natural hazards for large

Active Vibration Control of a Flexible Base Manipulator

Active Vibration Control of a Flexible Base Manipulator
Ph.D. Dissertation Defense Lynnane E. George 10 July 2002
Committee: Dr. Book, Dr. Calise (AE), Dr. Ferri, Dr. Singhose, Dr. Taylor (EE)
Overview Introduction
Background Literature Review (Ch 2) Flexible Base Manipul ator Modeling (Ch 3) Interactions and Inertial Singularities (Ch 4) Control Scheme (Ch 5) Simulations (Ch 6)